wherein the manipulator comprises at least one device configured to fasten at least two cable sets;

wherein the at least two cable sets are configured to run through at least one opening in the manipulator;

wherein the device includes at least two holders, through which the at least two cable sets run, respectively, and

wherein the at least two holders are detachably fixed along a section of an edge area of the at least one opening.

15. (New) The robot according to claim 14, wherein the opening is configured to be formed by a pipe socket fixedly mounted on the manipulator.

16. (New) The robot according to claim 14, wherein the at least two holders include a fastening means in the form of a curved collar.

17. (New) The robot according to claim 16, wherein the at least two holders are configured to be fixed by snap action with the curved collar.

18. (New) The robot according to claim 16, wherein the at least two holders are configured to be fixed with a hose clamp.

19. (New) The robot according to claim 14, wherein the device includes at least two lids configured to be detachably fixed in connection with the edge region of the at least one opening.

20. (New) The robot according to claim 19, wherein the at least two holders and the at least two lids have compatible shapes, and

the at least two holders and the at least two lids cover at least part of the at least one opening when mounted together.

21. (New) The robot according to claim 19, wherein the at least two holders and the at least two lids are configured to cover the opening and to form a tight seal of the opening.

22. (New) The robot according to claim 19, wherein the at least two lids are configured to be divided into sections.

23. (New) The robot according to claim 14, the at least two lids are configured to be divided into sections through at least one direction.

24. (New) A process for fastening in an industrial robot, the robot comprising:

a manipulator provided with a control system and at least two cable sets,

wherein the at least two cable sets are configured to run through at least one opening in the manipulator,

wherein the cable set is configured to run-through at least two holders, and

wherein the at least two holders are configured to be detachably fixed in connection with a section of an edge area of the at least one opening.

25. (New) The process according to claim 24, wherein at least two lids are configured to be compatible with the at least two holders, and wherein the at least two holders and the at least two lids are fixed in the opening to cover at least part of the at least one opening.

26. (New) The process according to claim 25, wherein the at least two holders and the at least two lids are configured to cover the at least one opening tight-fittingly when mounted together.

REMARKS

Favorable reconsideration of this application, in light of the present amendment and following discussion is respectfully requested.

Claims 14-26 are pending; Claims 1-13 have been canceled; and Claims 14-26 have been newly added. It is respectfully submitted that no new matter has been added by this amendment.